



TECHNICAL UNIVERSITY OF MOMBASA

**Faculty of Engineering &  
Technology in Conjunction with  
Kenya Institute of Highways and  
Building Technology (KIHBT)**

DEPARTMENT OF ELECTRICAL & ELECTRONIC ENGINEERING

HIGHER DIPLOMA IN ELECTRICAL & ELECTRONIC ENGINEERING

EEP 3203: SPECIAL ELECTRICAL MACHINES & DRIVES

END OF SEMESTER EXAMINATION

SERIES: AUGUST 2014

TIME: 2 HOURS

**Instructions to Candidates:**

You should have the following for this examination

- *Answer Booklet*
- *Electronic Calculator*
- *Drawing Instruments*

This paper consists of **FIVE** questions. Answer any **THREE** questions

All questions carry equal marks

Maximum marks for each part of a question are as shown

This paper consists of **THREE** printed pages

### Question One

- a) State TWO merits and ONE application of permanent magnet synchronous motor. **(3 marks)**
- b) (i) With the aid of a sketch, explain the working of a Switched Reluctance Motor.
- (ii) Explain any THREE benefits associated with the motor in b(i) above. **(7 marks)**
- c) The rotor of a synchro is excited by a single phase AC voltage of r.m.s of value 120V. Assume stator rotor turn ratio of unity and:
- (i) Determine the corresponding stator voltage for rotor angles:  
 $\alpha = +30^\circ$  and  $-30^\circ$   
respectively
- (ii) Find the terminal voltages when rotor angle  $\alpha = +40^\circ$  **(10 marks)**

### Question Two

- a) (i) State any THREE differences existing between DC and AC drives.
- (ii) Draw a labeled block diagram of a Thyristor Based DC Drive System. **(6 marks)**  
**(6 marks)**
- b) Show that for Field controlled DC servo motor the output speed  $\omega(s)$  is related to input voltage  $V_f(s)$  through:
- $$\frac{\omega(s)}{V_f(s)} = \frac{K_m f / L_f J_m}{\left(s + \frac{C}{J_m}\right) \left(s + \frac{R_f}{L_f}\right)}$$
- (8 marks)**
- c) A 200V field controlled, separately excited servo motor is fed from a DC Chopper Drive whose turn-off time  $t_{off}$  is constant for 30ms. Given the constant  $K_{mf} = 20$ ;  $L_f = 500$ ;  $J_m = 0.02$ ;  $R_f = 1\text{K}$   $\Omega$ ; and  $C = 0.2$ .  
 $\theta = 5\pi$   
Determine Drive time  $t_N$  required to turn the motor through angle  $\theta$  radians.

### Question Three

- c) (i) State any THREE advantages of electric drives over mechanical counterparts.
- (ii) List THREE merits of Gate Turn Off (G.T.O) devices over Thyristors in construction of Electronic Drives. **(6 marks)**
- d) (i) Use a classification diagram to categorize Electric Drives according to sources
- (ii) List any FOUR advantages of AC drives other DC **(6 marks)**

- c) From the corresponding equivalent circuit show that the torque produced in variable voltage/frequency control is given by:

$$T_e = KV_s^2$$

control is given by:

Hence determine the torque output of 950rpm, 6 pole, 50 Hz, 3 phase, 415V 15kW output motor when line voltage is reduced to 350V **(8 marks)**

#### Question Four

- a) Explain the principle applied:

- (i) Cycloconversion
  - (ii) Field Oriented Control (FOC)
  - (iii) Direct Torque Control (DTC)
- (3 marks)**

- b) (i) With the aid of a sketch describe the function of several sections of a 50Hz voltage source inverter VS1
- (ii) Sketch the output, input DC, and triggering scheme for circuit in b(i) corresponding to Pulse Width Modulation (PWM) and 25Hz output. **(10 marks)**

- c) A 3 phase square wave inverter is being supplied from a 415V source. The load voltage, current, frequency and power factor are 200V, 30A, 40Hz and 0.9 respectively. Determine:
- (i) Voltage on DC side
  - (ii) DC component of current
  - (iii) The source side current (rms)
  - (iv) The firing angle
- (7 marks)**

#### Question Five

- a) Define the following terms for stepper motors:

- (i) Step Angle
  - (ii) Resolution
  - (iii) Unipolar Drive
- (3 marks)**

- b) (i) With the aid of a construction and waveform show how 4 pole variable reluctance stepper functions with full stepping
- (ii) Specify how mini step and half step operation modes are achieved for b(i) above. **(8 marks)**

- c) A permanent magnet stepper motor has 6 poles each having 5 teeth and rotor having 50 teeth. The motor is coupled to the wheels of a robot with diameters of 7cm. The robot is required to cover a distance of 13.2m in 30 seconds. Determine:
- (i) Step Angle
  - (ii) Resolution
  - (iii) Stepping Frequency required
  - (iv) Frequency of supply
- (9 marks)**