



THE MOMBASA POLYTECHNIC UNIVERSITY COLLEGE

(A constituent College of JKUAT) FACULTY OF ENGINEERING AND TECHNOLOGY

DEPARTMENT OF MECHANICAL AND AUTOMOTIVE ENGINEERING DIPLOMA IN MECHANICAL ENGINEERING (PLANT) DIPLOMA IN MECHANICAL ENGINEERING (AUTOMOTIVE)

ECI 2231: CONTROL SYSTEM II

YEAR II SEMESTER II

SPECIAL/SUPPLEMENTARY EXAMINATION MAY 2012 SERIES TIME: 2 HOURS

INSTRUCTIONS TO CANDIDATES:

You should have the following for this examination:

- Answer Booklet
- Drawing Instruments

This paper consists of **FIVE** questions

Attempt ANY THREE questions. Maximum marks for each part of a question are as shown.

This paper consists of 3 printed Pages **Question ONE**

- a) i. Define the following terms used control system:
 - (i) Stable system
 - (ii) Unstable system
 - Marginally stable system (iii)

(3marks)

b) Determine the number of right-half plane poles in the closed loop transfer function.

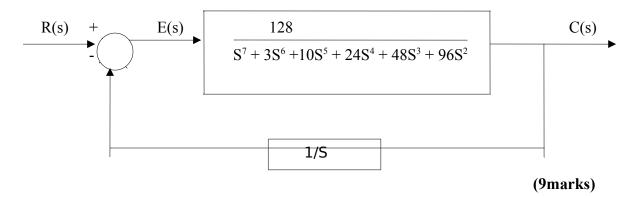
$$T(S) = 10$$

S⁵ + 2S⁴ + 3S³ + 6S² + 5^S + 3 (8marks)

c) For the system in figure I

Determine the stability i.

ii. Determine the number of right-half-plane poles



Question TWO

For unity feedback system with the open loop function

Κ

$$G(s) = \frac{K}{S(1+0.2S)(1+0.02S)}$$

i) For K = 1 Construct bode log – magnitude and phase plots

Evaluate the gain margin and phase margin. ii)

(20marks)

Ouestion THREE

For the system

G(s) =200

- i) Produce a polar plot for W=3 to W=10.
- Determine the phase margin and gain margin ii)

Question FOUR

- a) Define the following terms Poles of a transfer function i) ii) Zens of a transfer function. (2marks) b) Given F(s) = (S+2)(S+4)-S(S+3)(S+6)Find F(s) at the point S = -7 + j9.
- c) For the closed loop transfer function
 - 0.25JK (S + 0.435) T(s) = $S^4 + 3.46S^3 + 3.457S^2 + (0.719 + 0.25K)S + (0.0416 + 0.109K)$

Find the range of gain K1 that will cause the system to be stable. (10marks)

Question FIVE

For the system

G(s) =K(S+10)(S+20)(S+1)(S-10)

Construct the root locus and hence determine

- i) Poles
- ii) Zeros
- iii) Angle of A symptotes
- iv) Root locus on the real axis
- Break away points v)
- vi) Points where the root locus crosses imaginary axis
- vii) The value of K limiting the stability

(20marks)

(20marks)

(8marks)

(1+2S)(3+S)(5+S)