



TECHNICAL UNIVERSITY OF MOMBASA

School of Applied and Health Sciences

Department of Mathematics and Physics

UNIVERSITY EXAMINATION FOR:

Bachelor of Science in Technology in Applied Physics

EEE 4251: Control I

SPECIAL/SUPPLEMENTARY EXAMINATION

SERIES: JULY 2025

TIME: 2 HOURS

DATE : July 2025

Instructions to Candidates

You should have the following for this examination

-Answer Booklet, examination pass and student ID

This paper consists of **five** Questions; Question ONE is compulsory. In addition, attempt any Other TWO Questions.

Do not write on the question paper.

QUESTION ONE (Compulsory 30 marks)

- With the aid of a suitable diagrams illustrate the difference between open loop control systems and closed loop control systems [6 marks]
- Obtain the differential equations describing the electrical system shown in Fig. Q1 (b) and hence determine its transfer function [6 marks]

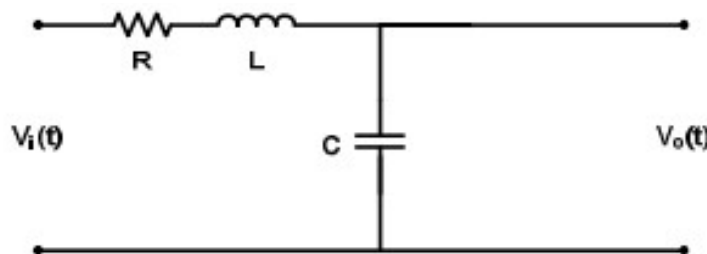


Fig. Q1 (b)

- The car speed cruise control input-output differential equation is given by:

$$\frac{d}{dt} v + \frac{b}{m} v = \frac{b}{m} v_r$$

For a step input $v_r(t)$. Using the Laplace transform determine the car speed response [8 marks]

- d) A control engineer designed a ship steering system represented by the block diagram in Fig. Q1 (d). using block diagram reduction techniques, determine its transfer function $Y(s)/R(s)$ [10 marks]

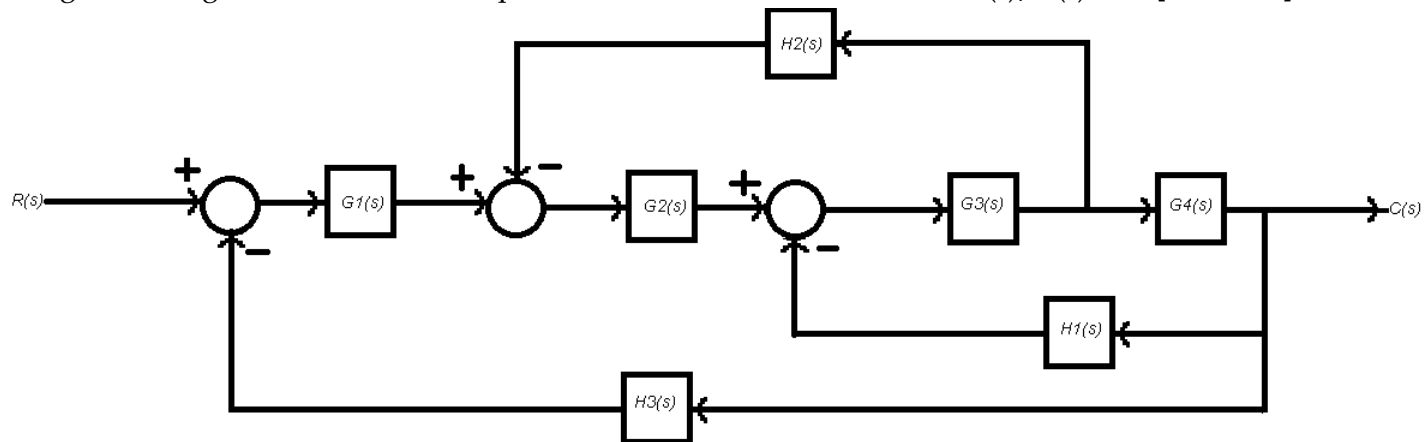


Fig. Q1 (d)

Question TWO

- a) Find the system transfer function between the capacitance voltage to the source voltage in the RLC circuit as shown in Fig. Q2(a) [7 marks]

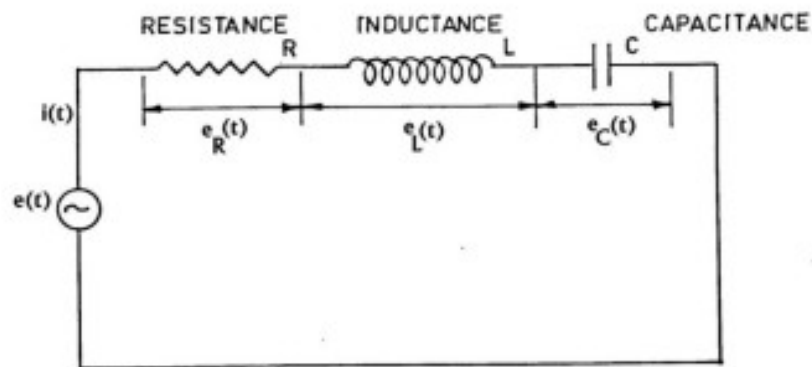


Fig. Q2 (a)

- b) Expand the following equations of Laplace transforms in terms of their partial fractions and obtain its time-domain responses.

i)
$$Y(s) = \frac{2s}{(s+1)(s+2)}$$

ii)
$$Y(s) = \frac{2s}{(s+1)^2(s+2)}$$

8 Marks]

- c) A second-order system has a damping factor of 0.3 (underdamped system) and an un-damped natural frequency of 10 rad/s. Keeping the damping factor the same, if the un-damped natural frequency is changed to 20 rad/s;
- locate the new poles of the system
 - comment on the response of the new system.

[5 marks]

Question THREE

a) The system Fig. Q3(a) is subjected to a unit step input and $\zeta = 0.5$ and $\omega_n = 4.5$ rad/sec. Determine the:

- (i) Rise time
- (ii) Peak time
- (iii) Maximum overshoot
- (iv) Settling time.

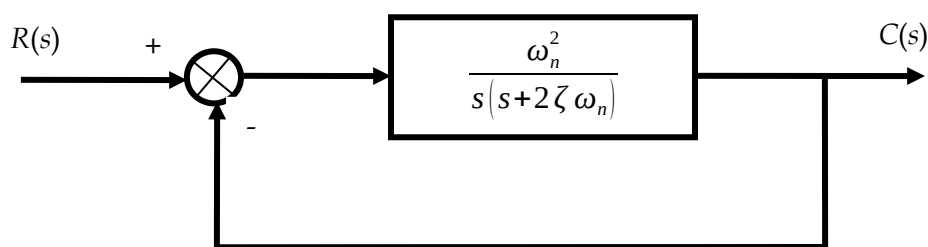


Fig. Q3(a)

[8 marks]

b) A single degree of freedom spring-mass-damper system has the following data: spring stiffness 25 kN/m; mass 0.025 kg; damping coefficient 18 N-s/m. Determine:

- (i) undamped natural frequency in rad/s and Hz
- (ii) damping factor
- (iii) damped natural frequency n rad/s and Hz.

[6 marks]

c) Using Routh-Hurwitz stability criterion, find the stability of the following system given by

$$B(s) = s^3 + 2s^2 + 3s + 10$$

[6 marks]

Question FOUR

a) Obtain the transfer function $Y(s)/U(s)$ of the motorcycle suspension system in Fig Q5(a). The input u is a displacement input.

[12 marks]

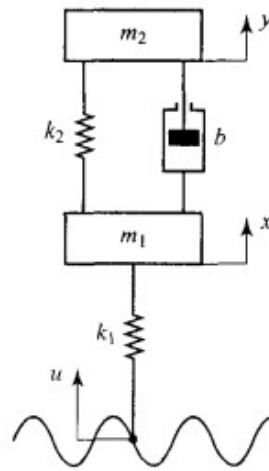


Fig Q5(a)

b) Define the following terms:

- (i) Gain margin
- (ii) Phase margin

[2 mark]

c) Evaluate analytically the expressions of magnitude and phase response for a system with feed forward transfer function

$$G(s) = \frac{1}{s(s+2)(s+4)}$$

[6 mark]

Question FIVE

a) Draw the root-locus of the feedback system whose open-loop transfer function is given by

$$G(s)H(s) = \frac{k}{s^4 + 5s^3 + 8s^2 + 6s}$$

[11 marks]

b) If

$$\frac{Y(s)}{U(s)} = \frac{s+3}{s^2+3s+2}$$

obtain the signal flow graph representation of this transfer function.

[9 marks]