TECHNICAL UNIVERSITY OF MOMBASA

INSTITUTE OF COMPUTING AND INFORMATICS

DEPARTMENT OF COMPUTING SCIENCE AND INFORMATION TECHNOLOGY

UNIVERSITY EXAMINATION FOR:

BACHELOR OF TECHNOLOGY IN INFORMATION TECHNOLOGY

EIT 4411: MICROPROCESSOR SYSTEM DESIGN

SPECIAL/SUPPLEMENTARY EXAMINATION

SERIES: SEPTEMBER 2018

TIME: 2 HOURS

DATE: SEPTEMBER 2018

Instructions to Candidates

You should have the following for this examination

-Answer Booklet, examination pass and student ID

This paper consists of FIVE questions. Question ONE is Compulsory attempt any other TWO questions.

Do not write on the question paper.

Question ONE

a) Distinguish between Programmed I/O and Interrupt driven I/O interfaces

4 marks

b) With aid of a block diagram of master-slave bus arrangement describe the sequence of steps involved for the processor to move data from memory to I/O device

8 marks

c)

i. With aid of block diagram describe the functions of the key elements of a basic control loop

ii. Explain any TWO reasons for measurement and control of industrial processes

12 marks

d) With aid of a block diagram of an I/O Module structure, explain how it interacts with internal computer resources and the external devices

6 marks

Question TWO

a) Explain the function of the following components of controller loop equipments

i. Transducer

ii. Converter

iii. Indicators

iv. Actuator

v. Recorder

. 10 marks

b) In the system of Figure Q2 the clock is connected to the timer IN input of the Intel 8155. If the system clock has a frequency of 3MHZ, write a program segment for the Intel 8155 that produces a continuous square wave with a frequency of 1kHz.Include a start timer command , disable the interrupt ports, use port C and B as output ports, and Port A as an input port

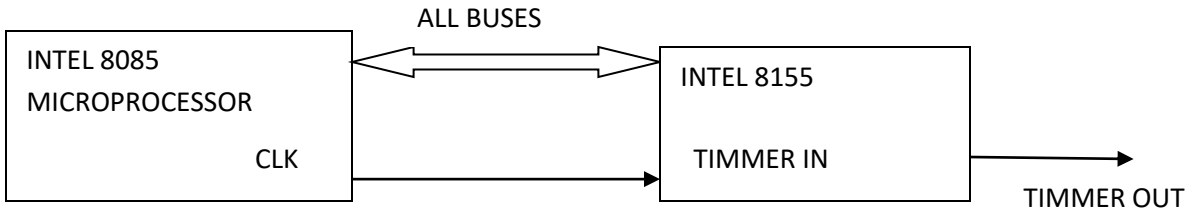

Figure Q2

10 marks

Question THREE

a) With the aid of sketches distinguish between Frequency and Time division multiplexing of data

6 marks

b) Assuming a microprocessor based system is interfaced with a device that can raise n- number of interrupt requests. With aid of a flowchart describe the algorithm of a software interrupt polling technique for the system.

10 marks

c) Outline any TWO advantages and TWO disadvantages of the technique in b)

4 marks

Question FOUR

a) Describe any FOUR significant parameters that you would consider while choosing the right microprocessor for your application,

8 marks

b) Define the following memory terms

i. Cell
ii. Data transfer time
iii. Settling time
iv. latency
v. Access time

5 marks

c) With aid of diagrams explain the **THREE** bus system organization in digital systems.

7 marks

Question FIVE

a) With aid of a block diagram describe System Design and Instrumentation for Stepper Motor Control with Furnace and Temperature Controller

10 marks

b) With aid of block diagram compare the operation of a fuzzy logic controller to the conventional logic controller

6 marks

c) Distinguish between top-down and bottom- up design method with respect to microprocessor based systems

4 marks

8085A CPU INSTRUCTIONS IN OPERATION CODE SEQUENCE

Table 5-2

OP CODE	MNEMONIC		OP CODE	MNEMONIC		OP CODE	MNEMONIC		OP CODE	MNEMONIC		OP CODE	MNEMONIC		OP CODE	MNEMONIC	
00	NOP		28	DCX	H	56	MOV	D,M	81	ADD	C	AC	XRA	H	D7	RST	2
01	LXI	B,D16	2C	INR	L	57	MOV	D,A	82	ADD	D	AD	XRA	L	D8	RC	
02	STAX	B	2D	DCR	L	58	MOV	E,B	83	ADD	E	AE	XRA	M	D9	–	
03	INX	B	2E	MVI	L,D8	59	MOV	E,C	84	ADD	H	AF	XRA	A	DA	JC	Adr
04	INR	B	2F	CMA		5A	MOV	E,D	85	ADD	L	B0	ORA	B	DB	IN	D8
05	DCR	B	30	SIM		5B	MOV	E,E	86	ADD	M	B1	ORA	C	DC	CC	Adr
06	MVI	B,D8	31	LXI	SP,D16	5C	MOV	E,H	87	ADD	A	B2	ORA	D	DD	–	
07	RLC		32	STA	Adr	5D	MOV	E,L	88	ADC	B	B3	ORA	E	DE	SBI	D8
08	–		33	INX	SP	5E	MOV	E,M	89	ADC	C	B4	ORA	H	DF	RST	3
09	DAD	B	34	INR	M	5F	MOV	E,A	8A	ADC	D	B5	ORA	L	E0	RPO	
0A	LDAX	B	35	DCR	M	60	MOV	H,B	8B	ADC	E	B6	ORA	M	E1	POP	H
0B	DCX	B	36	MVI	M,D8	61	MOV	H,C	8C	ADC	H	B7	ORA	A	E2	JPO	Adr
0C	INR	C	37	STC		62	MOV	H,D	8D	ADC	L	B8	CMP	B	E3	XTHL	
0D	DCR	C	38	–		63	MOV	H,E	8E	ADC	M	B9	CMP	C	E4	CPO	Adr
0E	MVI	C,D8	39	DAD	SP	64	MOV	H,H	8F	ADC	A	BA	CMP	D	E5	PUSH	H
0F	RRC		3A	LDA	Adr	65	MOV	H,L	90	SUB	B	BB	CMP	E	E6	ANI	D8
10	–		3B	DCX	SP	66	MOV	H,M	91	SUB	C	BC	CMP	H	E7	RST	4
11	LXI	D,D16	3C	INR	A	67	MOV	H,A	92	SUB	D	BD	CMP	L	E8	RPE	
12	STAX	D	3D	DCR	A	68	MOV	L,B	93	SUB	E	BE	CMP	M	E9	PCHL	
13	INX	D	3E	MVI	A,D8	69	MOV	L,C	94	SUB	H	BF	CMP	A	EA	JPE	Adr
14	INR	D	3F	CMC		6A	MOV	L,D	95	SUB	L	C0	RNZ		EB	XCHG	
15	DCR	D	40	MOV	B,B	6B	MOV	L,E	96	SUB	M	C1	POP	B	EC	CPE	Adr
16	MVI	D,D8	41	MOV	B,C	6C	MOV	L,H	97	SUB	A	C2	JNZ	Adr	ED	–	
17	RAL		42	MOV	B,D	6D	MOV	L,L	98	SBB	B	C3	JMP	Adr	EE	XRI	D8
18	–		43	MOV	B,E	6E	MOV	L,M	99	SBB	C	C4	CNZ	Adr	EF	RST	5
19	DAD	D	44	MOV	B,H	6F	MOV	L,A	9A	SBB	D	C5	PUSH	B	F0	RP	
1A	LDAX	D	45	MOV	B,L	70	MOV	M,B	9B	SBB	E	C6	ADI	D8	F1	POP	PSW
1B	DCX	D	46	MOV	B,M	71	MOV	M,C	9C	SBB	H	C7	RST	0	F2	JP	Adr
1C	INR	E	47	MOV	B,A	72	MOV	M,D	9D	SBB	L	C8	RZ		F3	DI	
1D	DCR	E	48	MOV	C,B	73	MOV	M,E	9E	SBB	M	C9	RET	Adr	F4	CP	Adr
1E	MVI	E,D8	49	MOV	C,C	74	MOV	M,H	9F	SBB	A	CA	JZ		F5	PUSH	PSW
1F	RAR		4A	MOV	C,D	75	MOV	M,L	A0	ANA	B	CB	–		F6	ORI	D8
20	RIM		4B	MOV	C,E	76	HLT		A1	ANA	C	CC	CZ	Adr	F7	RST	6
21	LXI	H,D16	4C	MOV	C,H	77	MOV	M,A	A2	ANA	D	CD	CALL	Adr	F8	RM	
22	SHLD	Adr	4D	MOV	C,L	78	MOV	A,B	A3	ANA	E	CE	ACI	D8	F9	SPHL	
23	INX	H	4E	MOV	C,M	79	MOV	A,C	A4	ANA	H	CF	RST	1	FA	JM	Adr
24	INR	H	4F	MOV	C,A	7A	MOV	A,D	A5	ANA	L	D0	RNC		FB	EI	
25	DCR	H	50	MOV	D,B	7B	MOV	A,E	A6	ANA	M	D1	POP	D	FC	CM	Adr
26	MVI	H,D8	51	MOV	D,C	7C	MOV	A,H	A7	ANA	A	D2	JNC	Adr	FD	–	
27	DAA		52	MOV	D,D	7D	MOV	A,L	A8	XRA	B	D3	OUT	D8	FE	CPI	D8
28	–		53	MOV	D,E	7E	MOV	A,M	A9	XRA	C	D4	CNC	Adr	FF	RST	7
29	DAD	H	54	MOV	D,H	7F	MOV	A,A	AA	XRA	D	D5	PUSH	D			
2A	LHLD	Adr	55	MOV	D,L	80	ADD	B	AB	XRA	E	D6	SUI	D8			

D8 = constant, or logical/arithmetic expression that evaluates to an 8-bit data quantity.

D16 = constant, or logical/arithmetic expression that evaluates to a 16-bit data quantity.

Adr = 16-bit address.