



TECHNICAL UNIVERSITY OF MOMBASA

FACULTY OF ENGINEERING AND TECHNOLOGY

ELECTRICAL ENGINEERING DEPARTMENT

UNIVERSITY EXAMINATION FOR:

DIPLOMA IN TECHNOLOGY IN ELECTRICAL AND ELECTRONIC ENGINEERING

EEP2304: ELECTRICAL MACHINE DRIVES

END OF SEMESTER EXAMINATION

SERIES: AUGUST 2019

TIME: 2 HOURS

DATE: Pick Date Select Month Pick Year

Instructions to Candidates

You should have the following for this examination

-Answer Booklet, examination pass and student ID

This paper consists of **five** Questions; Question ONE is compulsory. In addition attempt any Other TWO Questions.

Do not write on the question paper.

Question ONE

a)

- i. State any **THREE** good characteristics of Insulated Gate Bipolar Transistors (IGBT's) over other electronic devices applied in electrical drives
- ii. Sketch a Current Source Inverter Circuit(VSI) for a 3- ϕ synchronous motor, and explain the function of each section

(9 Marks)

- b) A $150V_{l-n}$, 10A, 40Hz, 1- ϕ , 0.85pf motor is fed via a four step inverter circuit from a 3- ϕ , 240 V_{l-n} supply. Calculate:

- i. The DC section voltage and current
- ii. The source side fundamental current and power factor
- iii. The source side fundamental current and power factor if source is replaced by 415 V_{ll} , 3- ϕ supply

(11 Marks)

Question TWO

- a)
- List any FOUR parameters considered in a dynamic model for electrical drives
 - State FOUR advantages of space phasor models over dynamic models in electrical drives
- (8 Marks)
- b) Two phase quadrature currents displaced from fixed reference frame by $\theta=30^\circ$ and each having peak value of 200 A are fed to a three phase machine with balanced supply. Sketch the layout of such a drive system and determine:
- $\alpha\beta o$ component output with dqo input
 - abc component output from $\alpha\beta o$ block
 - the layout sketch corresponding to drive in b(i) and b(ii) above

(12 Marks)

Question THREE

- a)
- Sketch a classification chart for various kinds of electric drives
 - Highlight any SIX factors to consider while selecting an electric drive for a certain application
- (8 Marks)
- b)
- With the aid of a sketch explain the functioning of Field controlled DC servo motor
 - Show that the transfer function of a Field Controlled Servo Motor is given by:

$$\frac{\theta_o(s)}{V_F(s)} = \frac{K_F K_m / L_F J_m}{s(s + D_m / J_m)(s + R_f / L_f)}$$

- iii. Determine the steady state angular displacement for the motor in b(i) above when supplied with a 100V step input. The parameters of the machine are:
 $L_f = 100\text{H}$, $R_f = 0.5\text{k}\Omega$, $K_f = 10$, $J_m = 0.01\text{Kg}\cdot\text{m}^2\cdot\text{s}^{-2}$, $D_m = 0.04\text{N}/\text{ms}^{-1}$, $K_m = 50$

(12 Marks)

Question FOUR

- a)
- State THREE Advantages of DC Chopper drives over DC Silicon Controlled Rectifier(SCR)
 - Sketch block diagram of DC SCR drive system and explain how it functions
- (9 Marks)
- a) A 210V, 20A, 500r.p.m. separately excited DC motor having armature resistance of 0.5Ω is to be connected via a SCR drive. Determine transformer ratio applied and the firing angle required for:
- forward motoring operation at 500rpm
 - forward braking at 300rpm

(11 Marks)

Question FIVE

- a)
- With the aid of a diagram explain how a Cyclo-converter drive functions
 - State ONE advantage and ONE disadvantage of the circuit above over variable voltage constant frequency SCR circuits
- (9 Marks)
- b) Sketch the equivalent circuit of an Induction motor derive the relationship between torque and frequency and:
- determine the torque output for 15hp, 415V, 730rpm, 50Hz induction motor when the control signal $k=0.25$, 0.5 and when $k=0.65$ and 1 respectively;
 - Sketch the Torque speed characteristic above assuming the motor was of NEMA class D

(11Marks)