

TECHNICAL UNIVERSITY OF MOMBASA

FACUULTY OF ENGINEERING AND TECHNOLOGY

ELECTRICAL ENGINEERING DEPARTRMENT

UNIVERSITY EXAMINATION FOR:

BACHELOR OF SCIENCE IN ELECTRICAL AND ELECTRONIC ENGINEERING

EEE 2414: ELECTRICAL MACHINES IV

SPECIAL/SUPPLEMENTARY EXAMINATION

SERIES: SEPTEMBER 2018

TIME: 2 HOURS

DATE: SEPTEMBER 2018

Instructions to Candidates

You should have the following for this examination

-Answer Booklet, examination pass and student ID

This paper consists of **five** Questions; Question ONE is compulsory. In addition attempt any Other TWO Questions.

Do not write on the question paper.

Question ONE (Compulsory 30 marks)

a)

- i. Distinguish between transient, steady state and dynamic stability in synchronous machines
- ii. Explain the consequence of loss of stability by a synchronous machine in a grid system
- iii. State any FIVE advantages in paralleling of synchronous machines on the grid

(9 Marks)

b) Show with the aid of a sketch that the swing equation of a synchronous machine can be expressed as: $M \frac{\partial^2 \delta(t)}{\partial t^2} + D \frac{\partial \delta(t)}{\partial t} = P_m - P_e = P_a$

(7 Marks)

- c) A 10MW, 50HZ synchronous machine is supplying a 1.0pu load when a switching event reduces the load by 20%. The output frequency increased steadily to 52Hz in time t=30cycles. Calculate the:
 - i. Inertia constant H
 - ii. Kinetic energy of rotating masses
 - iii. The rotor angular displacement at a time t=10cycles
 - iv. The rotor speed after t=10cycles

(9 Marks)

d) Use a P-Q operating chart to show the FOUR operating limits of a synchronous machine

(5 Marks)

Question TWO

- a)
 - i. highlight how TWO different kinds of synchronous machine rotors are applied to improve system stability
 - ii. explain with aid of sketches the effect of multiple machines on the overall system moment of inertia

(9 Marks)

a) THREE synchronous machine are connected in a multi-machine system are shown Fig Q2 below:





Take the equivalent damping constant (D_{eq}) of the system is 0.2pu, and the equivalent frequency regulation constant (R_{eq}) of 10% based on largest unit rating, to find the equivalent moment of inertia M and the steady frequency of the system when mechanical power suddenly reduces by ¹/₄. The inertia constants are based on corresponding generator ratings.

Question THREE

a)

- i. With the aid of a sketch, explain the equal area principle in machine stability analysis
- ii. State the reasons why only the first swing of synchronous machine is considered in stability analysis

(8 Marks)

(12 Marks)

- b) A machine is rated 1.5pu is delivering 1.0pu power when suddenly mechanical input power increases by 0.2 pu.
 - i. Determine the maximum swing angle δ for the first swing
 - ii. Explain whether the machine is stable following the disturbance

Question FOUR

a)i. Show that the power output of the generator is given by:

$$P = \frac{EV}{X_s} \sin\delta$$

ii. From equation (i) above explain how synchronous machine rotor angle stability may be improved

(8 Marks)

- b) A synchronous machine having synchronous reactance of 1.2Ω is supplying a 3 Phase, 11kV,12.5MVA, 0.8pf lagging load. Given that the transmission line has a reactance of 0.8Ω . Find
 - i. E behind the synchronous reactance
 - ii. The active power delivered
 - iii. The operating load angle
 - iv. Maximum possible power output of the machine

(12Marks)

Question FIVE

a)

- i. Describe the hunting Phenomena in synchronous machines
- ii. State any THREE causes and any THREE ways of minimizing hunting in synchronous machines
- iii. Sketch the generator droop characteristics showing the influence of a governor

(10 Marks)

b) The turbine governor valve system transfers functions of a 12pole, 50Hz generator system are given by:
1

 $K_V = \frac{1}{(s+1)}$

Given that the generator moment of inertia M=1.2 and Damping D=1 and regulating constant R=10%. Suddenly mechanical power decrease by 50% occurs.

- i. Sketch the system arrangement in control canonical form
- ii. Determine the steady state speed of the rotor
- iii. The steady state frequency error