

## TECHNICAL UNIVERSITY OF MOMBASA

# FACULTY OF ENGINEERING AND TECHNOLOGY DEPARTMENT OF MECHANICAL & AUTOMOTIVE ENGINEERING UNIVERSITY EXAMINATION FOR:

DIPLOMA IN NAUTICAL SCIENCE

ANS 2201 : ELECTRONIC NAVIGATION SYS & MARINE INSTRUMENTS END OF SEMESTER EXAMINATION

**SERIES:** DECEMBER 2016

TIME: 2 HOURS

**DATE:** Pick Date Dec 2016

### **Instructions to Candidates**

You should have the following for this examination

-Answer Booklet, examination pass and student ID

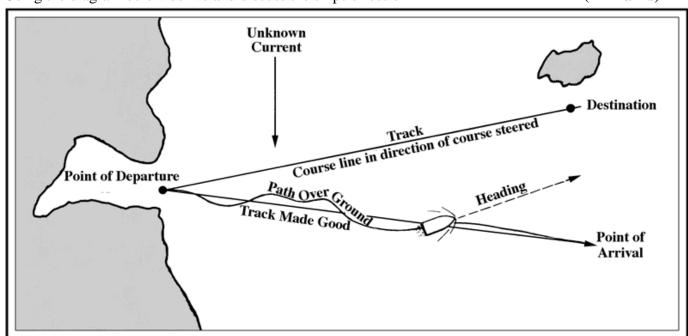
This paper consists of FIVE questions. Attempt any THREE questions.

Do not write on the question paper.

### **Question ONE**

a) Using the diagram below derive and discuss the ships direction

(12 Marks)



- b) Define the following acronyms
  - i. Loran
  - ii. GPS
  - iii. kHz
  - iv. MHz

### **Question TWO**

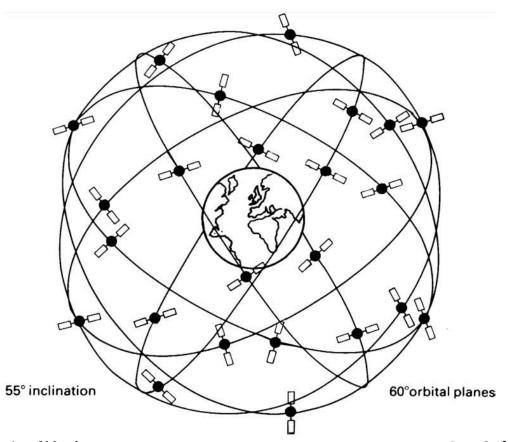
- a) Using an appropriate diagram define and illustrate the following
  - i. Longitude (long) (4 Marks)
  - ii. Difference of Longitude (DLong.) (4 Marks)
- b) Describe and discuss the GPS Signal architecture (12 Marks)

### **Question THREE**

- a) Define the term Loran lines of position (LOPs) (2 Marks)
- b) Using proper illustrations discuss the assumption that two transmitters A and B simultaneously transmit the same pulse stream. If the distance between the transmitters is 1000 nmiles, calculate the time taken to cover the distance between the transmitters where (t = d/v). (18 Marks)

### **Question FOUR**

Using the diagram below discuss the space segment of the GPS System (20 Marks)



(8 Marks)

# **Question FIVE**

a)	Define the term a hyperbolic navigation system	(2 Marks)
b)	Explain the basis theory of LORAN C navigation system	(10 Marks)
c)	Describe and define the component of LORAN C system	(8 Marks)